

EE1.e13 (EEE1023): Electronics III

Mechanics lecture 11

Revision

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www.ee.surrey.ac.uk/Teaching/Courses/ee1.e13



Review of mechanics topics



- Physical quantities and dimensions
- Static forces
- Kinematics
- Dynamics

Preparation for Revision



- What is **mechanics**?
 - organize the main topics that we have covered

- What are the key equations
 - identify general formulae
 - understand every symbol's meaning



Physical quantities and dimensions

Base quantities and dimensions:

Quantity	Dim.	Unit	Symbol
mass	M	kilogram	kg
length	L	metre	m
time	T	second	s
current	I	ampere	A
temperature	Θ	kelvin	K
substance	N	mole	mol
luminosity	J	candela	cd

Checking formulae:

$$\dim(LHS) = \dim(RHS)$$

Scaling:

$$\dim(\text{dimensionless quantity}) = \emptyset$$

Static forces

Fundamental forces: gravity, EM, weak & strong

Force vectors: line of action, components

$$F_x = \mathbf{F} \cdot \mathbf{i}$$

Moments of forces:

$$\mathbf{M} = \mathbf{r} \times \mathbf{F}$$

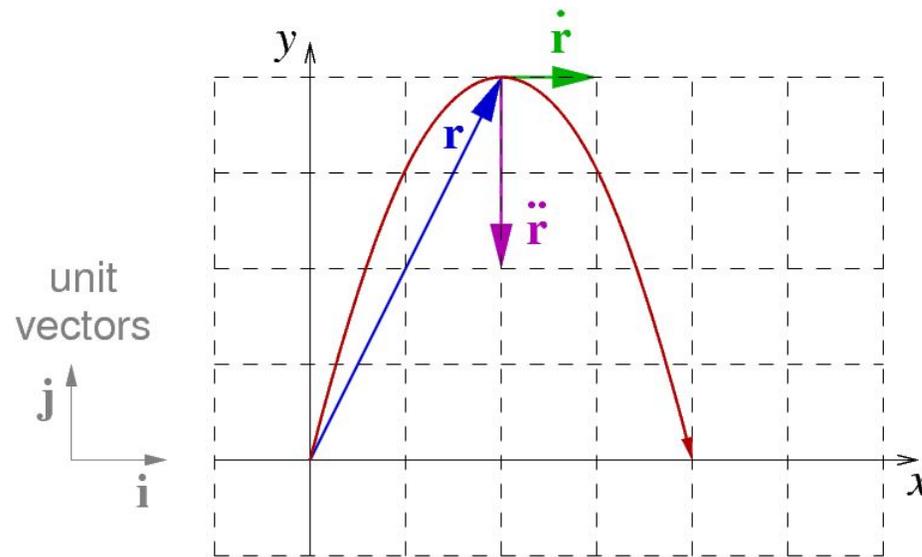
Equilibrium: zero resultant force and moment

$$\mathbf{R}_F = \sum_i \mathbf{F}_i = 0 \quad \text{and} \quad \mathbf{R}_M = \sum_j \mathbf{M}_j = 0$$

Kinematics

Acceleration, velocity and displacement vectors:

$$\ddot{\mathbf{r}}(t) = \frac{d\dot{\mathbf{r}}(t)}{dt} = \frac{d^2 \mathbf{r}(t)}{dt^2}$$



Rotational motion:

$$\dot{\mathbf{r}} = \boldsymbol{\omega} \times \mathbf{r}$$

Dynamics

Newton's laws of motion

1. Inertia: no force, constant velocity

2. Change: force causes change of momentum, $\mathbf{F} = \frac{d(m\dot{\mathbf{r}})}{dt}$

3. Opposition: equal and opposite forces

Work

$$W = \int \mathbf{F} \cdot d\mathbf{r} + \int \mathbf{T} \cdot d\theta$$

for conservative forces $\oint \mathbf{F} \cdot d\mathbf{r} = 0$

and potential energy $U = - \int \mathbf{F} \cdot d\mathbf{r}$

Simple Harmonic Motion

$$m\ddot{\mathbf{x}} + k\mathbf{x} = 0$$

Revision questions

1. The Surrey Space Rocket weighs 10 tonnes (10^4 kg) at launch and produces a constant thrust of $\mathbf{F} = 120\mathbf{j}$ kN.
 - (a) What are the dimensions of acceleration?
 - (b) What is the SI unit for acceleration?
 - (c) What is its initial acceleration as a vector $\dot{\mathbf{y}}$ at lift off? [Assume $g = 9.81 \text{ ms}^{-2}$.]
 - (d) After some time, it attains an altitude of 1 km. What is the mechanical work done by the rocket?
 - (e) Assuming no variation in the gravitational field at that distance, calculate the potential energy.
 - (f) Assuming no losses due to non-conservative (drag) forces but a reduced mass of 9.6 tonnes, estimate the rocket's kinetic energy and hence its speed \dot{y} .

Revision questions

2. Later in its mission, the docking module ($m_D = 1$ tonne) approaches the International Space Station (ISS). The displacement of its centre of gravity (CoG) relative to the docking point at the origin prior to contact at $t=0$ is $\mathbf{x}(t) = (2 - 0.05t)\mathbf{i} + vt\mathbf{j}$. However, a point P at the other end of the ISS has a displacement \mathbf{r} that varies over time due to its rotation in orbit:

$$\mathbf{r}(t) = -10 \cos \omega t \mathbf{i} - 10 \sin \omega t \mathbf{j} \quad (1)$$

where $\omega = 2\pi \times 10^{-3} \text{ k s}^{-1}$.

- (a) Give a vector expression for the velocity of point P over time.
- (b) What is the instantaneous (vector) velocity of P at $t = 0$?
- (c) Given $\mathbf{x}(t)$'s position on contact, what is the magnitude of the vertical velocity component v needed to match the ISS's rotation?

Revision questions

- 2.(d) Immediately after contact, the module's displacement is $\mathbf{x}(t) = 2\mathbf{i} + vt\mathbf{j}$. What is the change in the module's momentum?
- (e) Given that the angular inertia of the docking module is $I = 8m_D/3$, what would be the burn duration d required to increase the docking module's angular velocity about its CoG from 0 s^{-1} to $\omega\text{ s}^{-1}$ from a pair of thrusters with a combined torque strength of $T = 100\text{ Nm}$?

Summary of Revision

1. Dimensional analysis

- Base quantities
- Formula checking
- Scaling

2. Static forces

- Fundamental forces
- Force vectors
- Moments of forces
- Equilibrium

3. Kinematics of motion

- Acceleration, velocity and displacement
- Rotational motion

4. Dynamic forces

- Newton's laws of motion
- Work, conservative forces and potential energy
- Simple harmonic motion



Preparation for Acoustics (semester 2)

- What is a **sound wave**?
 - look up a definition of sound and its properties

- Example of a device for manipulating sound
 - write down or draw your example
 - explain how it modifies the sound

