

EE1.e13 (EEE1023): Electronics III

Mechanics lecture 9

Rigid body dynamics

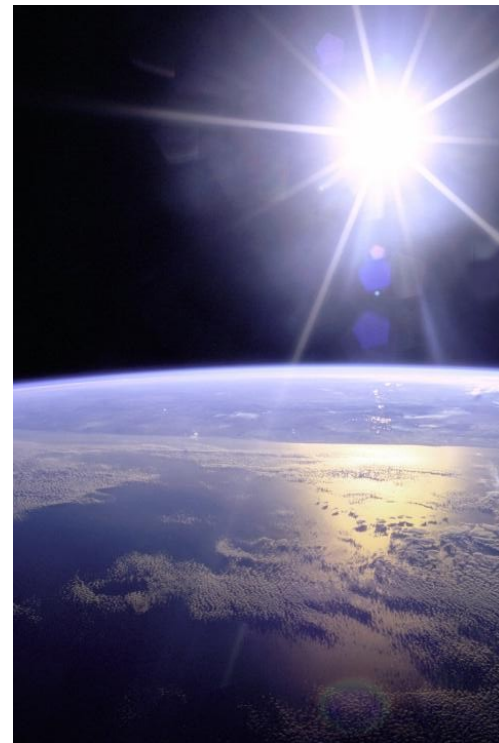
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Rotational dynamics

- Dynamics of circular motion
- Angular momentum
- Angular inertia
- Angular work & power
- Kepler's law
- Orbiting the earth



Preparation for Rigid body dynamics

- What is **angular momentum**?
 - look up the equation for it
 - define all the terms in the equation



- What is **angular inertia**?
 - look up its definition
 - give one example



Angular momentum

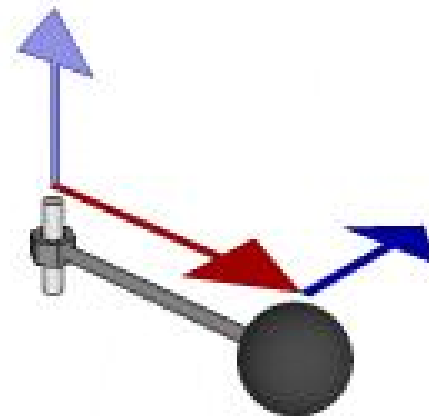
Angular momentum represents the *moment of momentum*

- Torque, the moment of force, is $\mathbf{T} = \mathbf{r} \times \mathbf{F}$
- Angular momentum is $\mathbf{L} = \mathbf{r} \times \mathbf{p}$
where linear momentum $\mathbf{p} = m \dot{\mathbf{r}}$

From Newton's 2nd law, we consider changes in moment of momentum:

$$\mathbf{T} = \frac{d\mathbf{L}}{dt} \quad (1)$$

$$\begin{aligned} \boldsymbol{\tau} &= \mathbf{r} \times \mathbf{F} \\ \mathbf{L} &= \mathbf{r} \times \mathbf{p} \end{aligned}$$



Angular inertia

Angular inertia represents the *moment of inertia*

- For a mass in circular motion, the angular inertia is

$$J = r^2 m$$

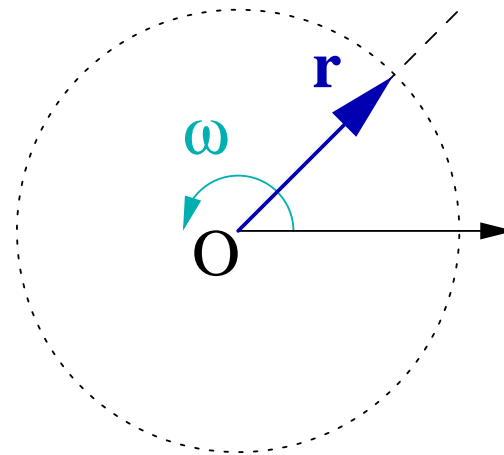
- Torque creates angular acceleration

$$\mathbf{T} = J\ddot{\theta} \quad (2)$$

which is the rate of change of angular velocity, $\ddot{\theta} = \dot{\omega}$

This gives us neat expression
for angular momentum:

$$\mathbf{L} = J\omega \quad (3)$$



Moments of inertia

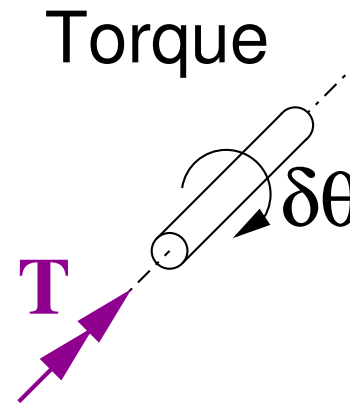
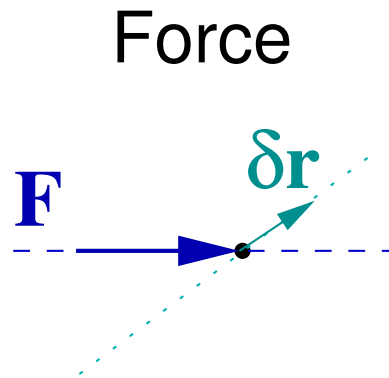
The moments of inertia of some common objects are listed with the axis through their centre of mass:

<i>object</i>	<i>J</i>
rod of length l	$\frac{ml^2}{12}$
solid disc of radius r	$\frac{mr^2}{2}$
hollow sphere of radius r	$\frac{2mr^2}{3}$
solid sphere of radius r	$\frac{2mr^2}{5}$

Work

The **work** done is equal to:

1. the force times the distance along its line of application
2. the parallel force component times the displacement



Linear work is $W_F = \mathbf{F} \cdot \delta \mathbf{r}$

Rotational work is $W_T = \mathbf{T} \cdot \delta \theta$

In general, the **total work** is their sum:

$$W = W_F + W_T \quad (4)$$

Power

Power is the rate of work

Average power over a short time interval δt is

$$P_F = \mathbf{F} \cdot \frac{\delta \mathbf{r}}{\delta t} \qquad P_T = \mathbf{T} \cdot \frac{\delta \theta}{\delta t}$$

Instantaneous power is the limit as $\delta t \rightarrow 0$:

$$\begin{aligned} P_F &= \mathbf{F} \cdot \frac{d\mathbf{r}}{dt} \\ &= \mathbf{F} \cdot \dot{\mathbf{r}} \qquad (5) \end{aligned}$$

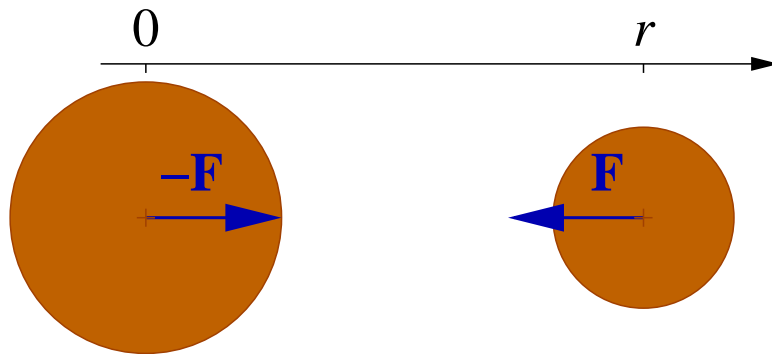
$$\begin{aligned} P_T &= \mathbf{T} \cdot \frac{d\theta}{dt} \\ &= \mathbf{T} \cdot \omega \qquad (6) \end{aligned}$$

In general, the **total power** is their sum:

$$P = P_F + P_T \qquad (7)$$

Examples

Motion in a conservative force field



Gravitational force:

$$F = \frac{GMm}{r^2} \quad (8)$$

where

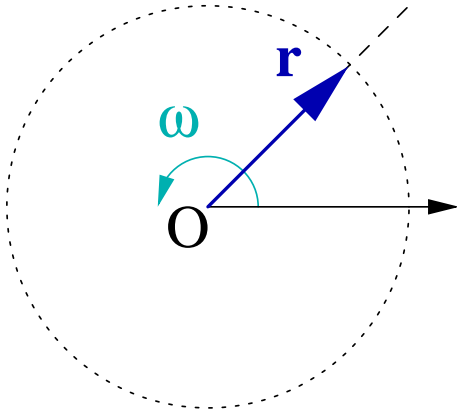
$$G = 6.67 \times 10^{-11} \text{ N kg}^{-2}$$

Including the direction of the force, we get the vector force on the smaller mass:

$$\mathbf{F}_G = \frac{GMm}{r^2} (-\mathbf{e}_r) \quad (9)$$

where the radial unit vector is defined $\mathbf{e}_r = \frac{\mathbf{r}}{r}$.

Inertial force for circular motion



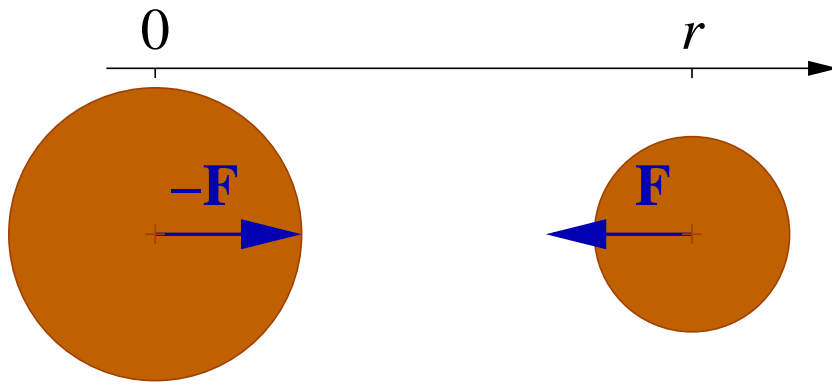
The kinematic expression for circular motion gives us

$$\begin{aligned}\mathbf{r}(t) &= r \cos \omega t \mathbf{i} + r \sin \omega t \mathbf{j} \\ \dot{\mathbf{r}}(t) &= -\omega r \sin \omega t \mathbf{i} + \omega r \cos \omega t \mathbf{j} \\ \ddot{\mathbf{r}}(t) &= -\omega^2 r \cos \omega t \mathbf{i} - \omega^2 r \sin \omega t \mathbf{j} \\ &= -\omega^2 (r \cos \omega t \mathbf{i} + r \sin \omega t \mathbf{j}) \\ &= -\omega^2 \mathbf{r}(t)\end{aligned}\tag{10}$$

So the inertial force needed to maintain circular motion is

$$\mathbf{F}_K = m\ddot{\mathbf{r}} = -m\omega^2 \mathbf{r}\tag{11}$$

Kepler's 3rd law for planetary orbits



Considering radial forces of a planet orbiting the sun:

$$F_G = \frac{GM_{\odot}}{r^2} m = F_K = m\omega^2 r = m \left(\frac{2\pi}{T} \right)^2 r \quad (12)$$

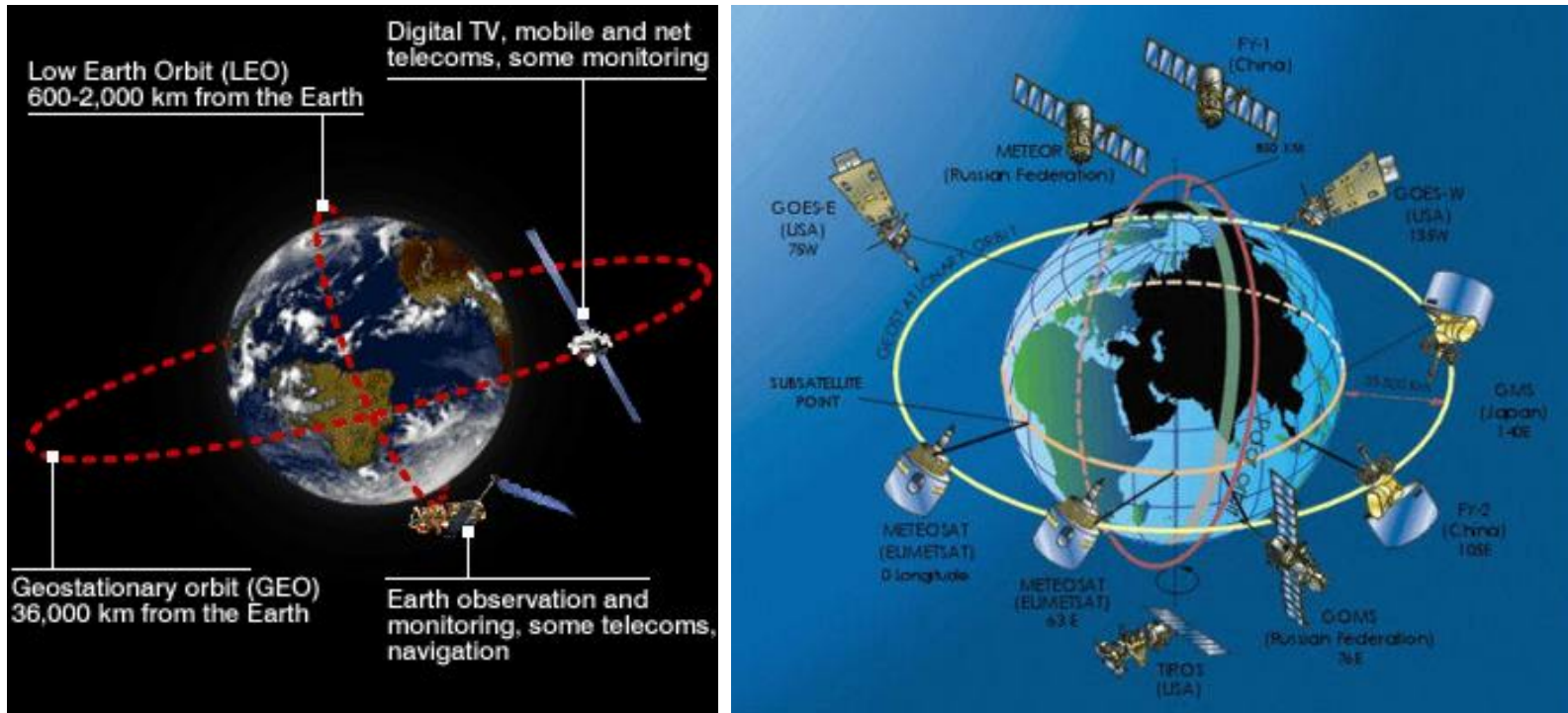
The period T depends on the radial distance r as

$$T^2 = \frac{4\pi^2}{GM_{\odot}} r^3 \quad (13)$$

$$G = 6.67 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2} \text{ and } M_{\odot} = 1.99 \times 10^{30} \text{ kg}$$

Low earth orbit (LEO)

For satellites orbiting close to the earth's surface



$$T^2 = \frac{4\pi^2}{GM_{\oplus}} r^3 \quad (14)$$

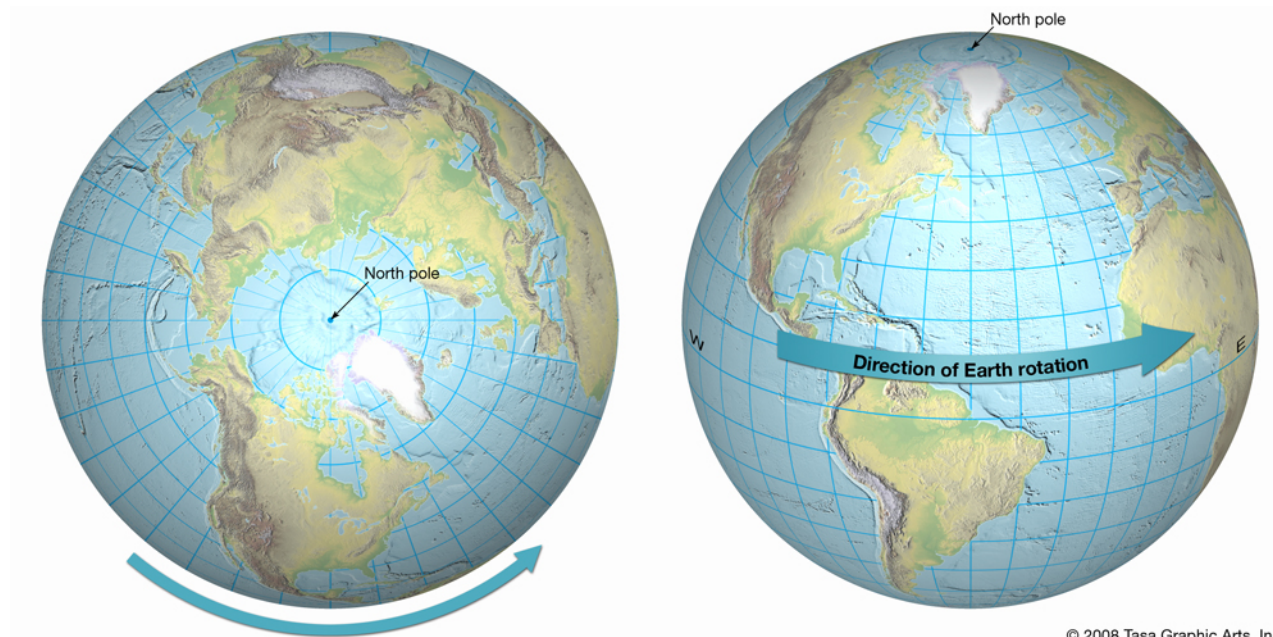
$$G = 6.67 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2} \text{ and } M_{\oplus} = 5.97 \times 10^{24} \text{ kg}$$

Geostationary earth orbit (GEO)

To match the earth's spin, the period is set to 24 hours

$$T_{\text{GEO}}^2 = \frac{4\pi^2}{GM_{\oplus}} r_{\text{GEO}}^3 \quad (15)$$

where $T_{\text{GEO}} = 24 \times 60 \times 60 \text{ s}$, $G = 6.67 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2}$
and $M_{\oplus} = 5.97 \times 10^{24} \text{ kg}$



Using potential energy to calculate escape velocity

Potential energy to move from earth's surface into space is

$$\begin{aligned} U_G &= - \int_{R_{\oplus}}^{\infty} \mathbf{F} \cdot d\mathbf{r} = \int_{R_{\oplus}}^{\infty} \frac{GM_{\oplus}m}{r^2} dr \\ &= \left[-\frac{GM_{\oplus}m}{r} \right]_{R_{\oplus}}^{\infty} = \frac{GM_{\oplus}m}{R_{\oplus}} \end{aligned} \quad (16)$$

Escape velocity is obtained by providing an equal amount of kinetic energy:

$$\begin{aligned} W_K &= \frac{1}{2} m v_{\text{esc}}^2 = U_G \\ \Rightarrow v_{\text{esc}} &= \sqrt{\frac{2GM_{\oplus}}{R_{\oplus}}} \end{aligned} \quad (17)$$

$G = 6.67 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2}$, $M_{\oplus} = 5.97 \times 10^{24} \text{ kg}$ and $R_{\oplus} = 6371 \text{ km}$

Summary of Rotational dynamics

- Dynamics of circular motion
- Angular momentum
- Angular inertia
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Preparation for Oscillation

- What is **simple harmonic motion** (SHM)?
 - look up the equation of motion for SHM



- Example of SHM
 - make a sketch of SHM
 - identify what forces are involved in your example

